

94-775/95-865 Lecture 5: Clustering Part I

George Chen

Announcements

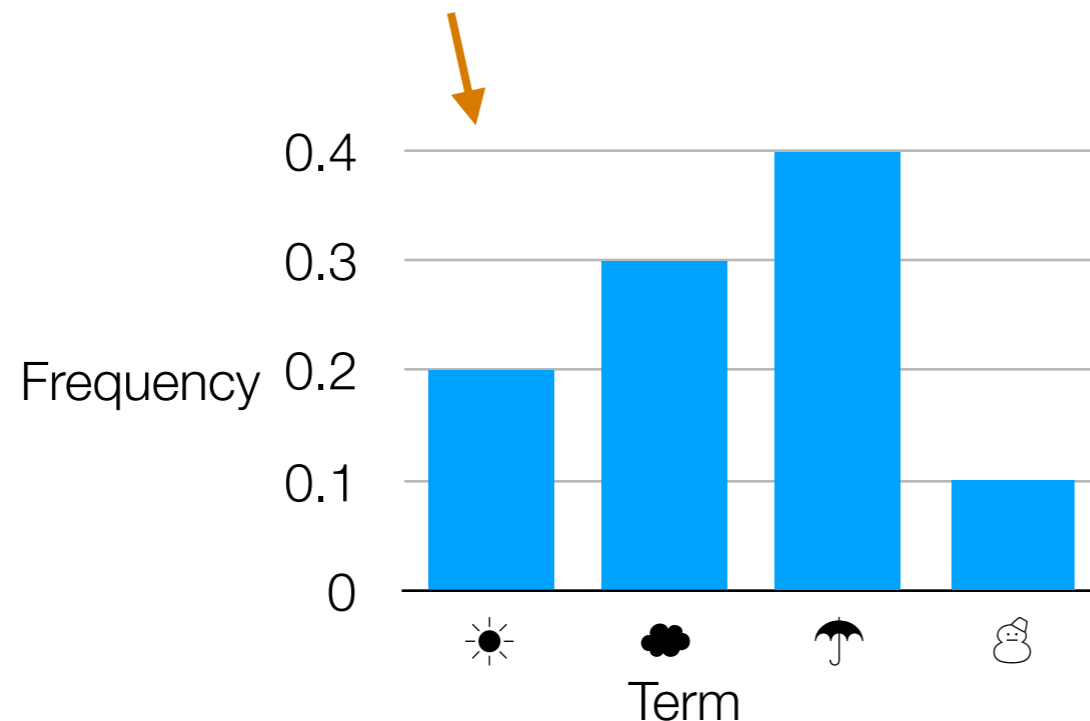
- HW1 solutions are up in Canvas (look in “Files”)
- Sample final project slide decks from last year are up in Canvas (look in “Files”)
- The final project proposal is now due Friday February 15
- Hard part initially: finding data that relates to a policy question you care about!

Let's look at images

(Flashback) Recap: Basic Text Analysis

- Represent text in terms of “features”
(such as how often each word/phrase appears)
- Can repeat this for different documents:
represent each document as a “feature vector”

"Sentence": ☀️☂️☁️☁️☁️☂️👶☂️☂️☀️



$$\begin{bmatrix} 0.2 \\ 0.3 \\ 0.4 \\ 0.1 \end{bmatrix}$$

This is a point in
4-dimensional
space, \mathbb{R}^4

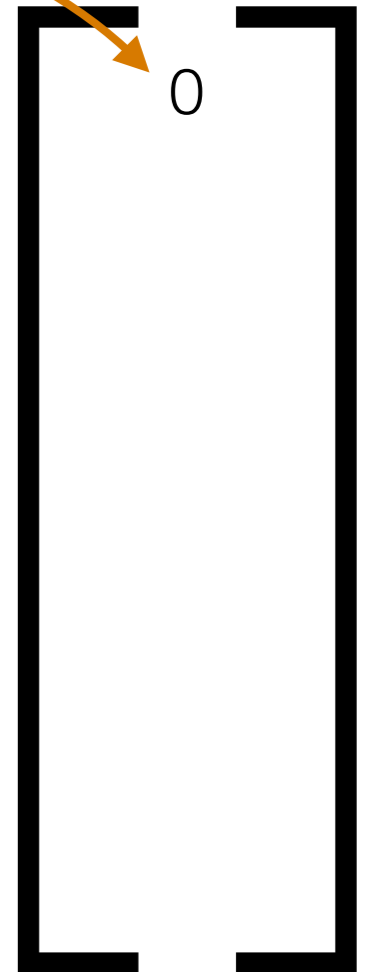
dimensions = number of terms

In general (not just text): first represent data as feature vectors

Example: Representing an Image



0: black
1: white

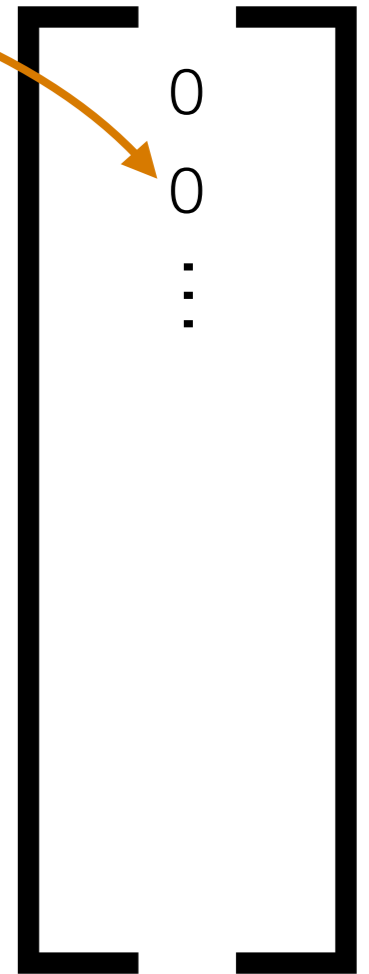


Go row by row and look at pixel values

Image source: starwars.com

Example: Representing an Image

0: black
1: white

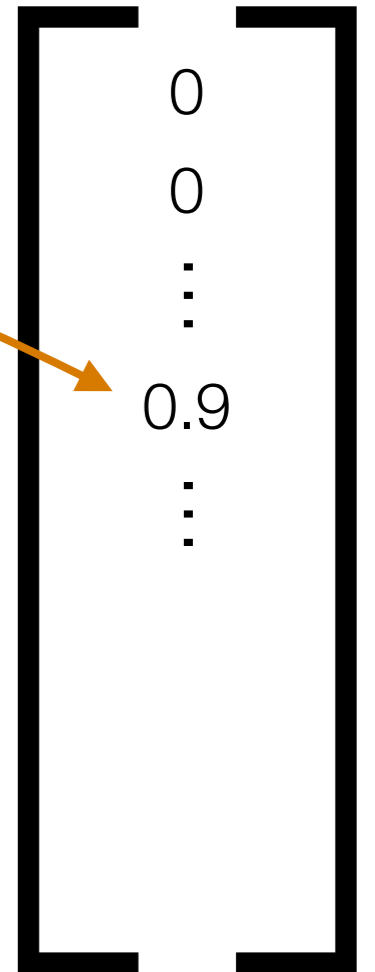
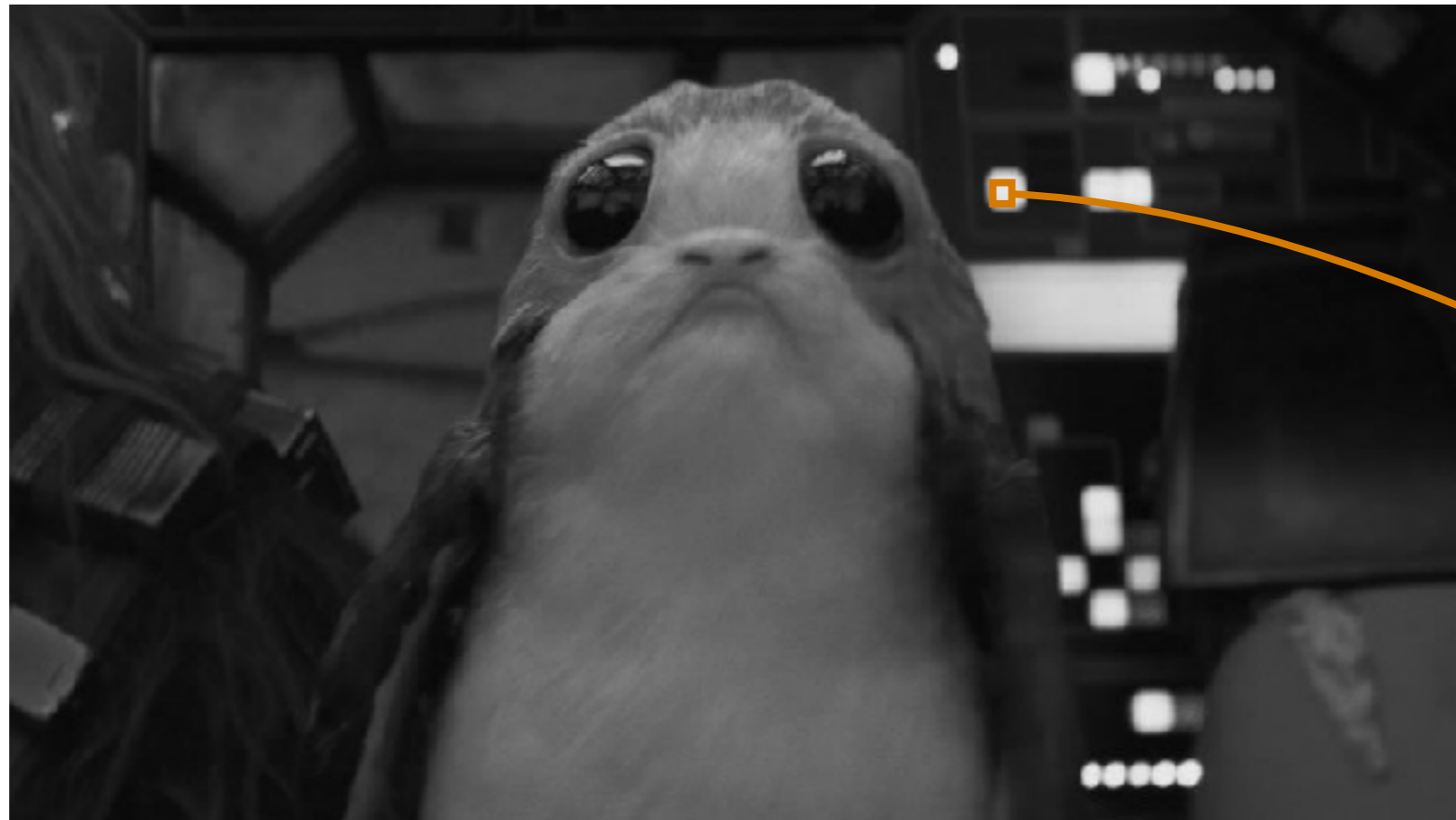


Go row by row and look at pixel values

Image source: starwars.com

Example: Representing an Image

0: black
1: white

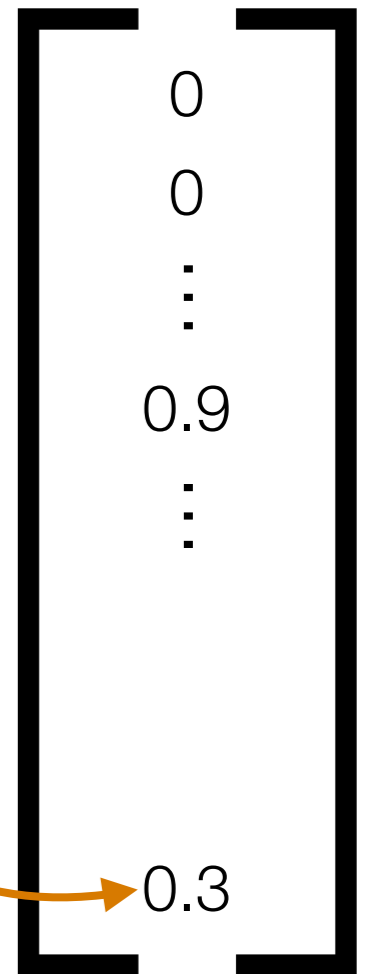


Go row by row and look at pixel values

Image source: starwars.com

Example: Representing an Image

0: black
1: white



Go row by row and look at pixel values

dimensions = image width \times image height

Very high dimensional!

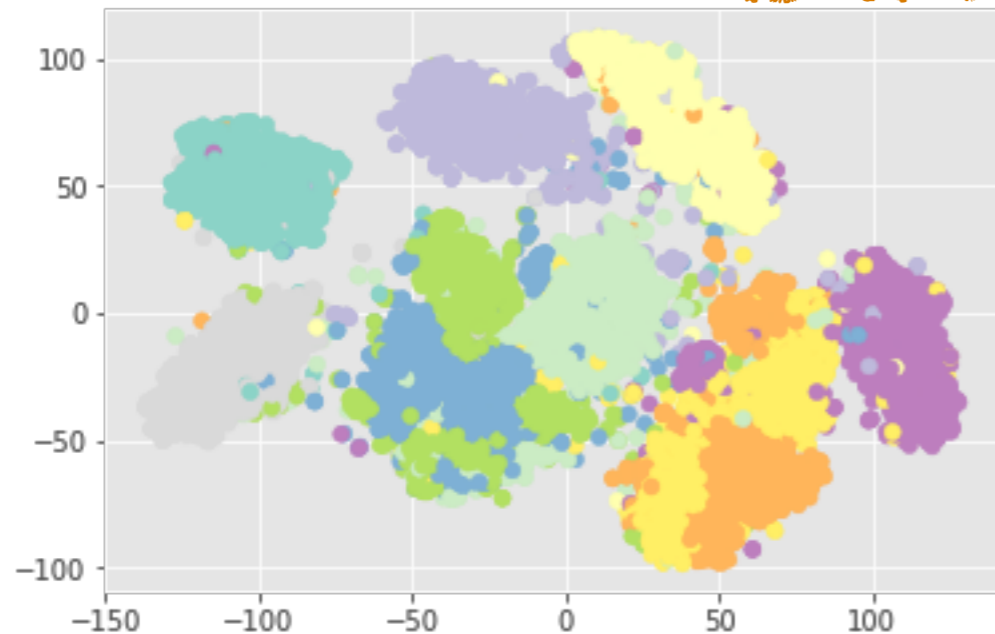
Image source: starwars.com

Dimensionality Reduction for Images

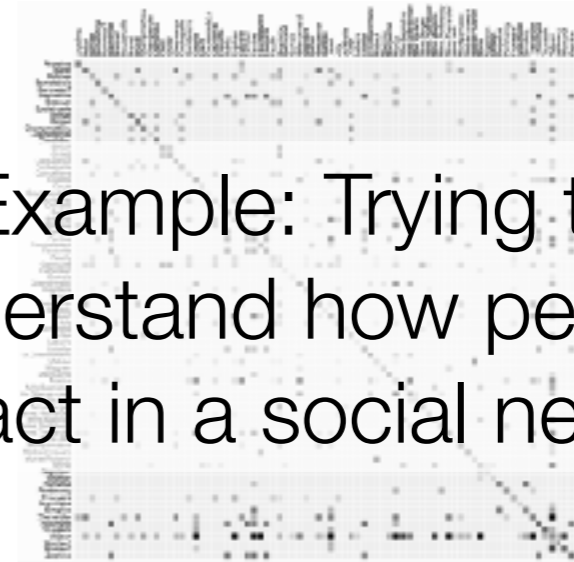
Demo

Visualization

is a way of debugging data analysis!



Example: Trying to understand how people interact in a social network



Important:

Handwritten digit demo is a **toy example** where we know which images correspond to digits 0, 1, ... 9

Many real UDA problems:

The data are **messy** and it's not obvious what the "correct" labels/answers look like, and "correct" is ambiguous!

This is largely why I am covering "supervised" methods (require labels) *after* "unsupervised" methods (don't require labels)

**Let's look at a *structured* dataset
(easier to explain clustering):
drug consumption data**

Drug Consumption Data

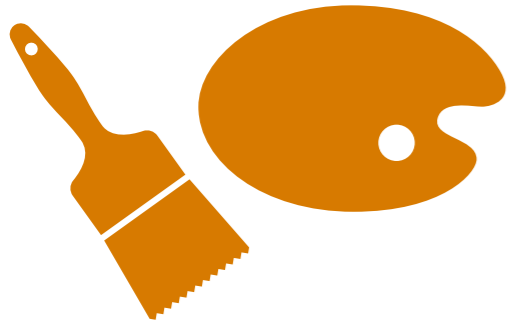
Demo

Clustering Shows Up Often in Real Data!

- Example: crime might happen more often in specific hot spots
- Example: people applying for micro loans have a few specific uses in mind (education, electricity, healthcare, etc)
- Example: users in a recommendation system can share similar taste in products
- Example: students have different skill levels
(clusters could correspond to different letter grades)

To come up with clusters, we first need to define what it means for two things to be “similar”

The Art of Defining Similarity



- There usually is no “best” way to define similarity

Example: cosine similarity $\frac{\langle Y_u, Y_v \rangle}{\|Y_u\| \|Y_v\|}$

- Also popular: define a distance first and then turn it into a similarity

Example: Euclidean distance $\|Y_u - Y_v\|$

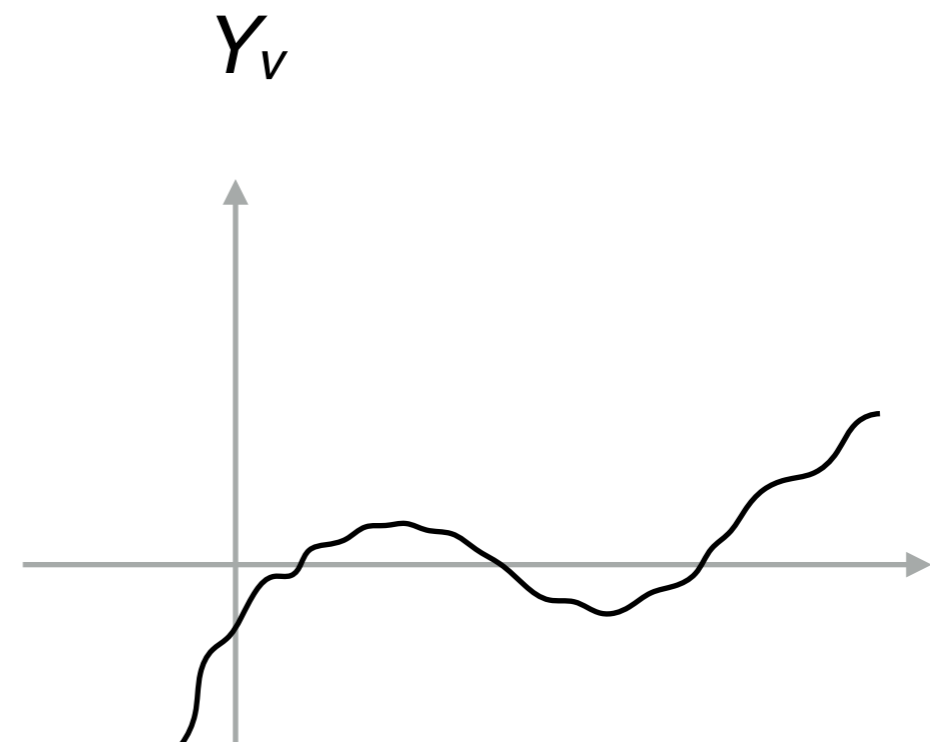
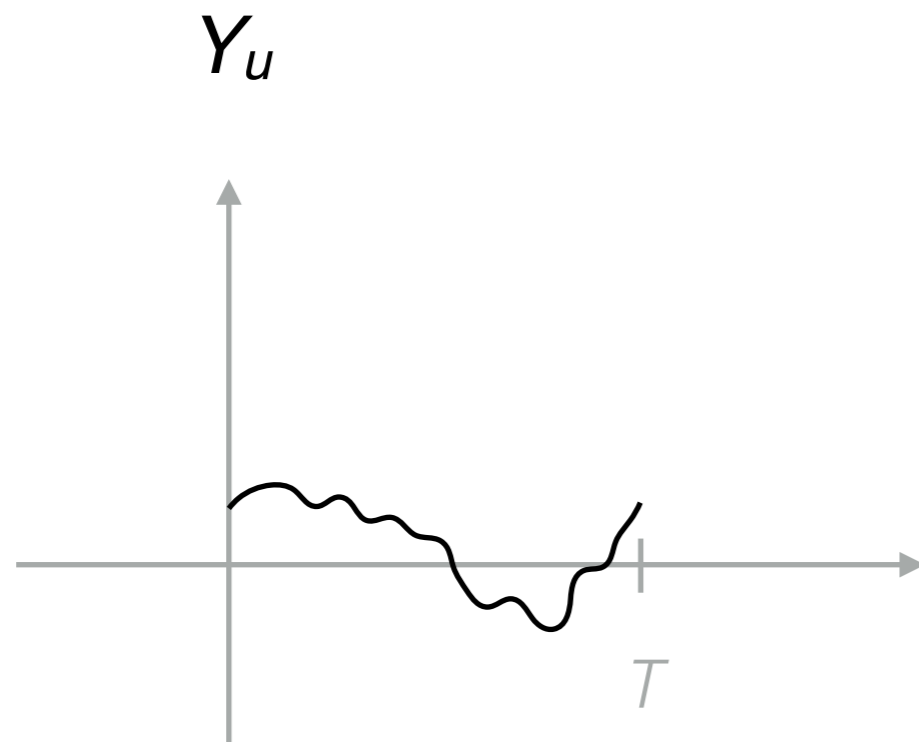
Turn into similarity with decaying exponential ↓

$$\exp(-\gamma \|Y_u - Y_v\|)$$

where $\gamma > 0$

Example: Time Series

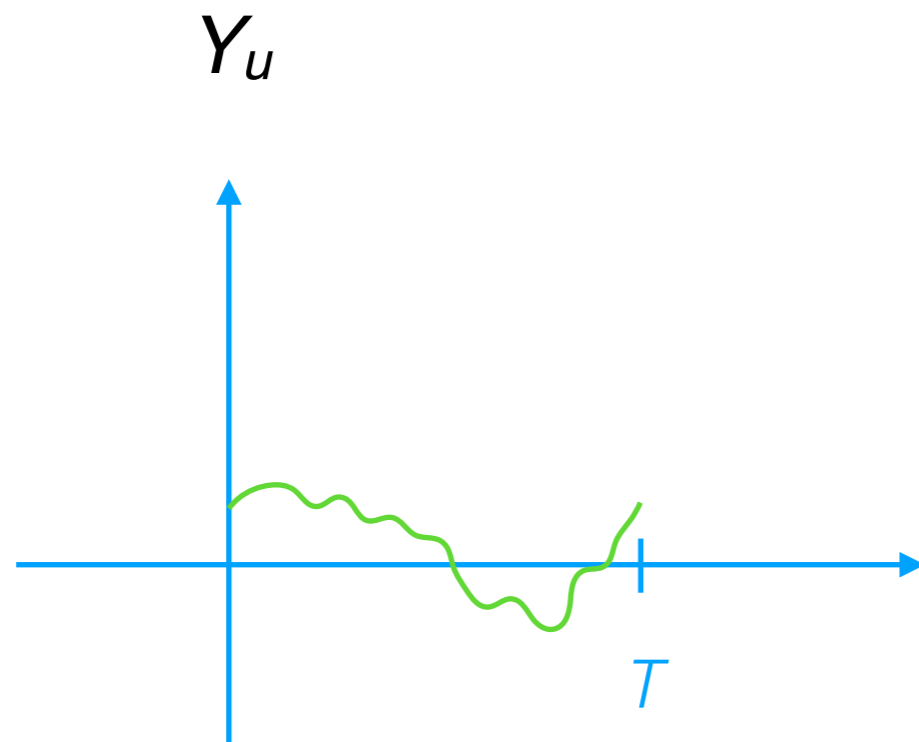
How would you compute a distance between these?



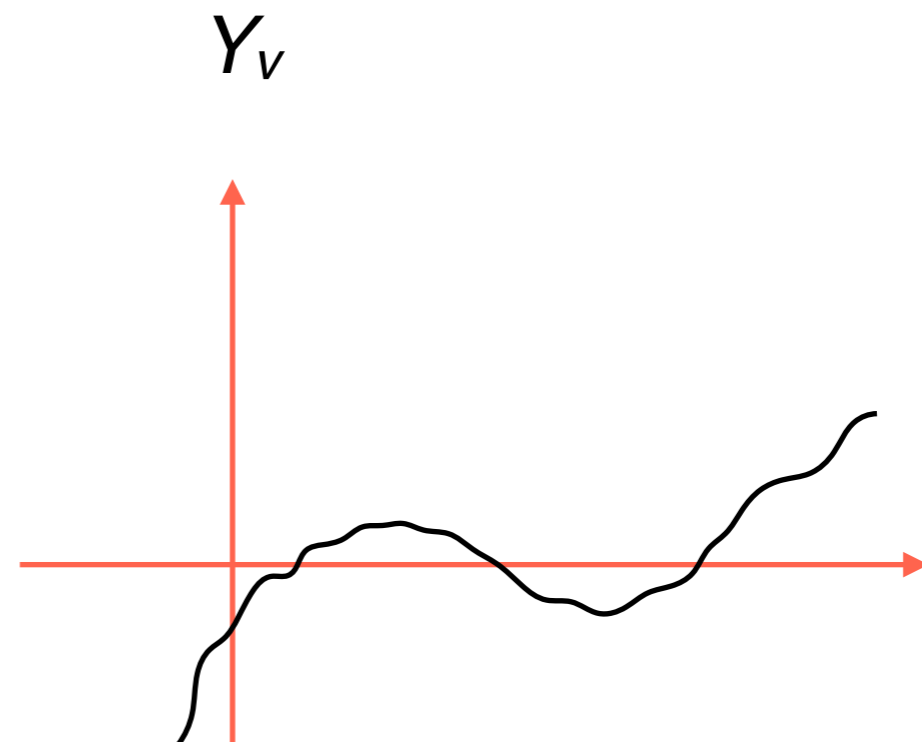
Only observe time steps
between 0 and T

Example: Time Series

How would you compute a distance between these?

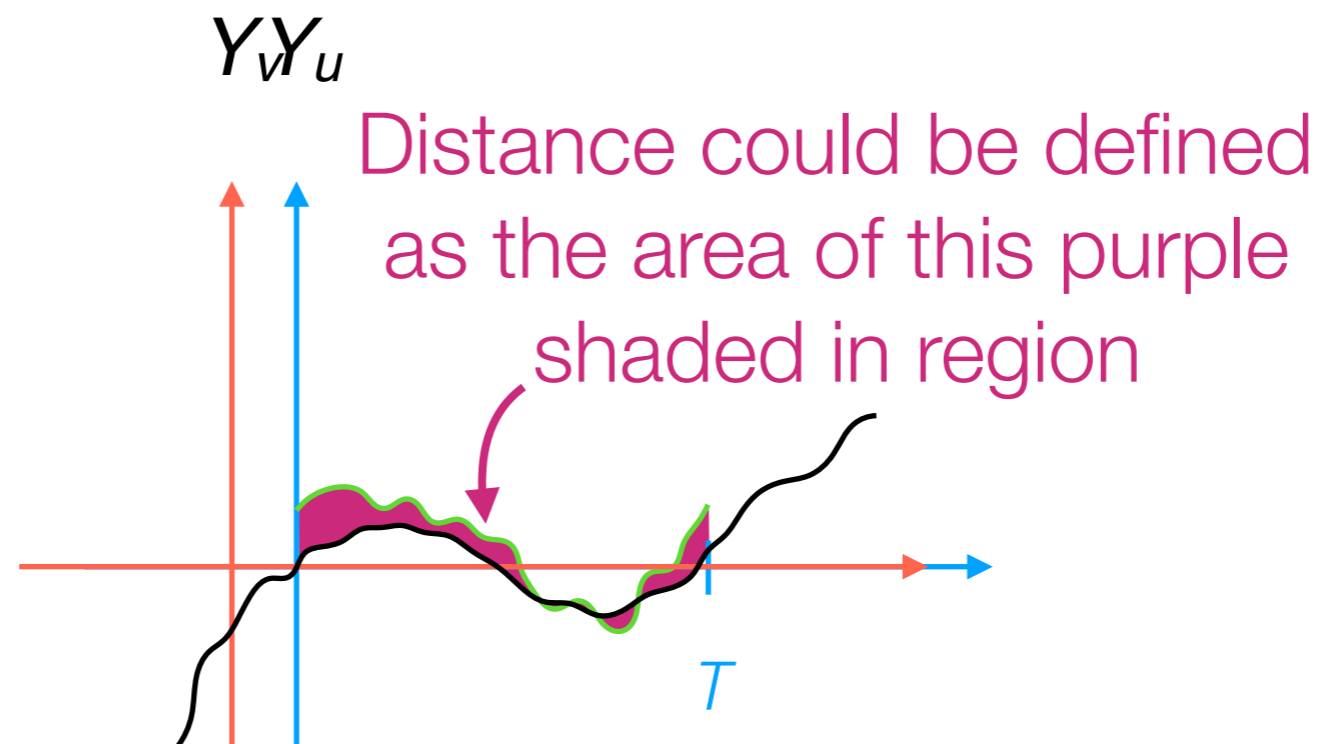


Only observe time steps
between 0 and T



Example: Time Series

How would you compute a distance between these?



One solution: Align them first

In practice: for time series, very popular to use "dynamic time warping" to first align (it works kind of like how spell check does for words)

Is a Similarity Function Any Good?

Easy thing to check:

- Pick a data point
- Compute its similarity to all the other data points, and sort them from most similar to least similar
- Inspect the most similar data points

If the most similar points are not interpretable, it's quite likely that your similarity function isn't very good =(

Going from Similarities to Clusters

There's a whole zoo of clustering methods

Two main categories we'll talk about:

Generative models

1. Pretend data generated by specific model with parameters
2. Learn the parameters ("fit model to data")
3. Use fitted model to determine cluster assignments

Hierarchical clustering

Top-down: Start with everything in 1 cluster and decide on how to recursively split

Bottom-up: Start with everything in its own cluster and decide on how to iteratively merge clusters

We start here

We're going to start with perhaps the most famous of clustering methods

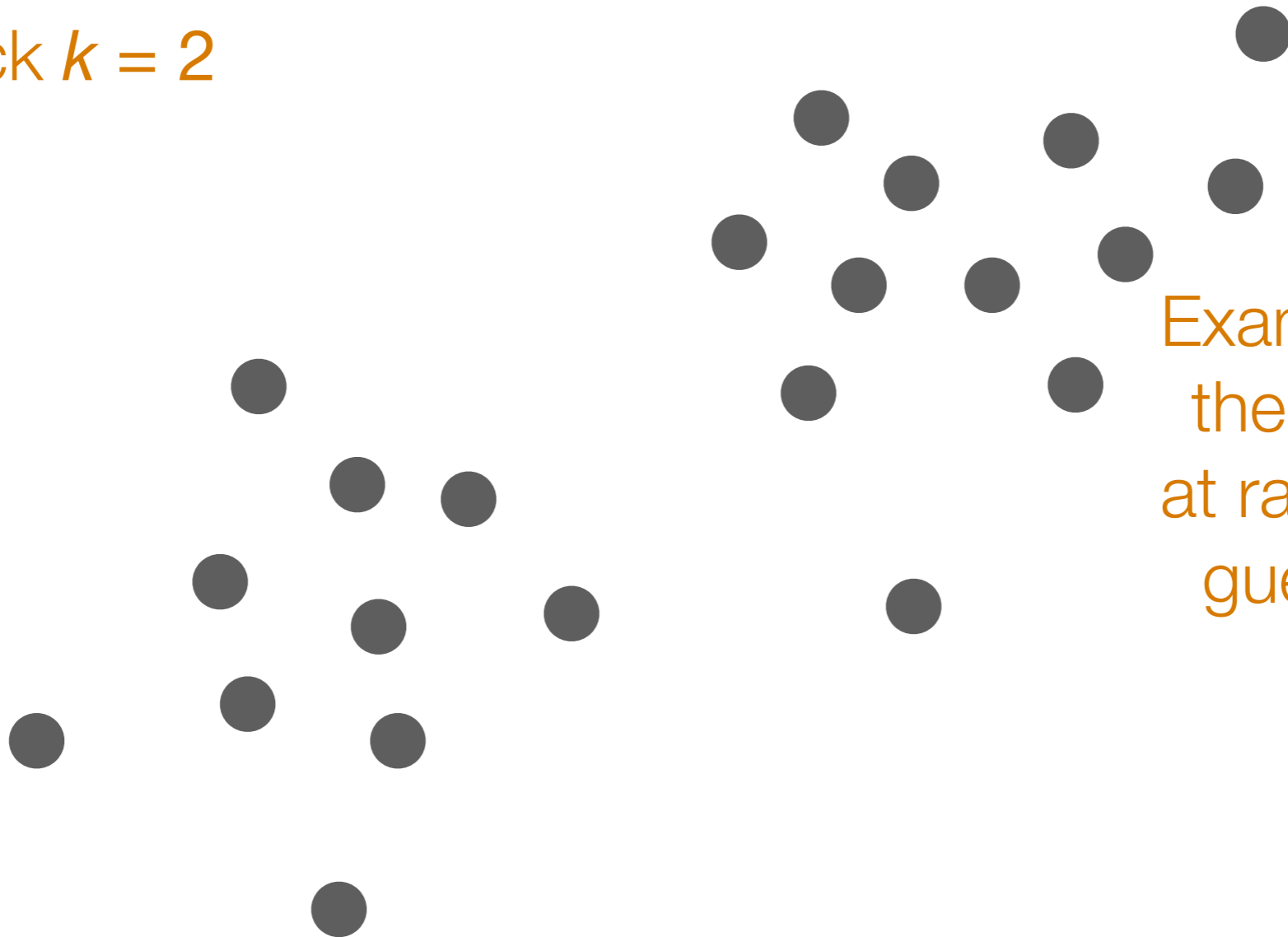
It won't yet be apparent what this method
has to do with generative models

k -means

Step 0: Pick k

We'll pick $k = 2$

Step 1: Pick guesses for where cluster centers are

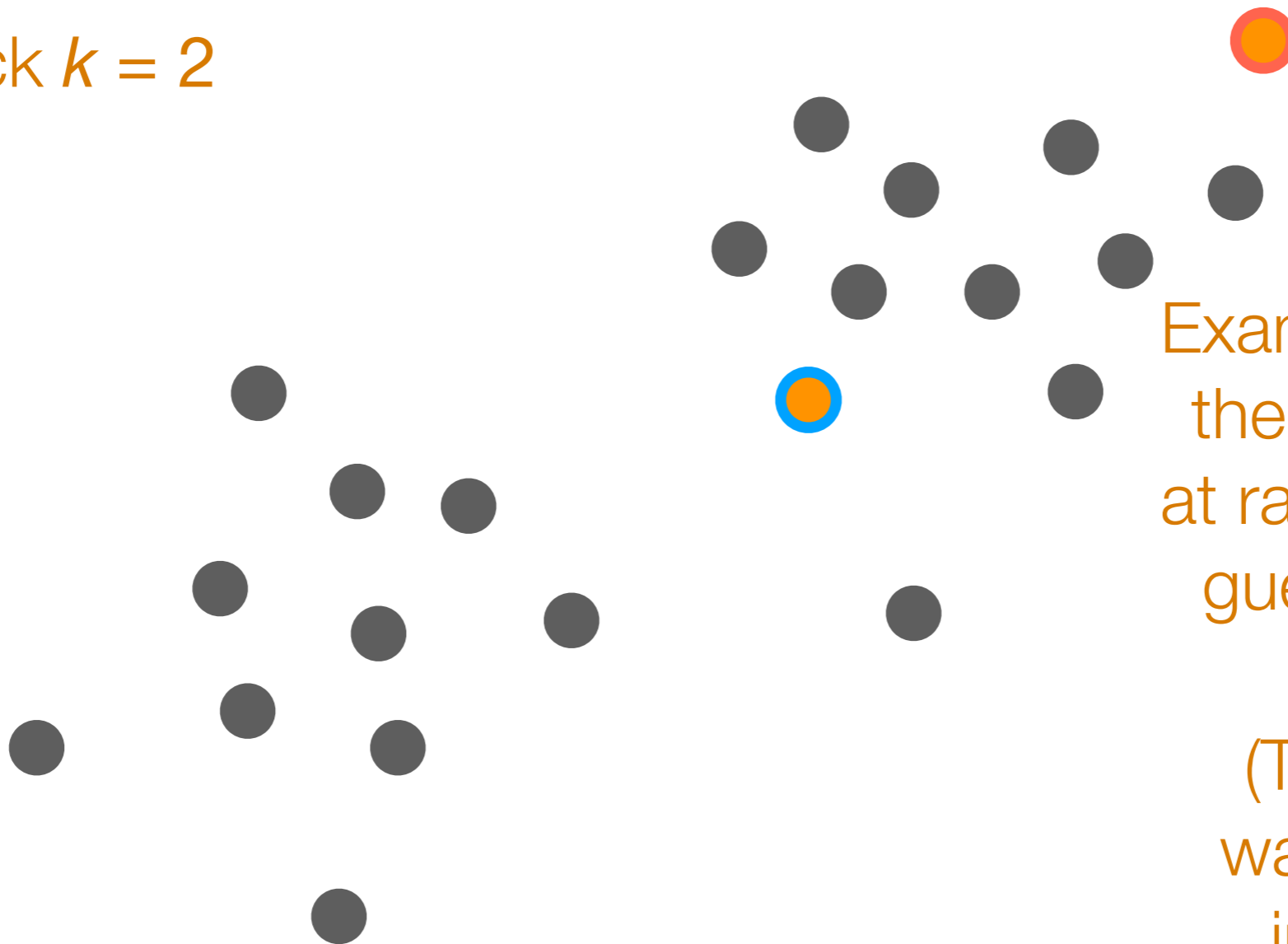


Example: choose k of the points uniformly at random to be initial guesses for cluster centers

k -means

Step 0: Pick k

We'll pick $k = 2$



Step 1: Pick guesses for where cluster centers are

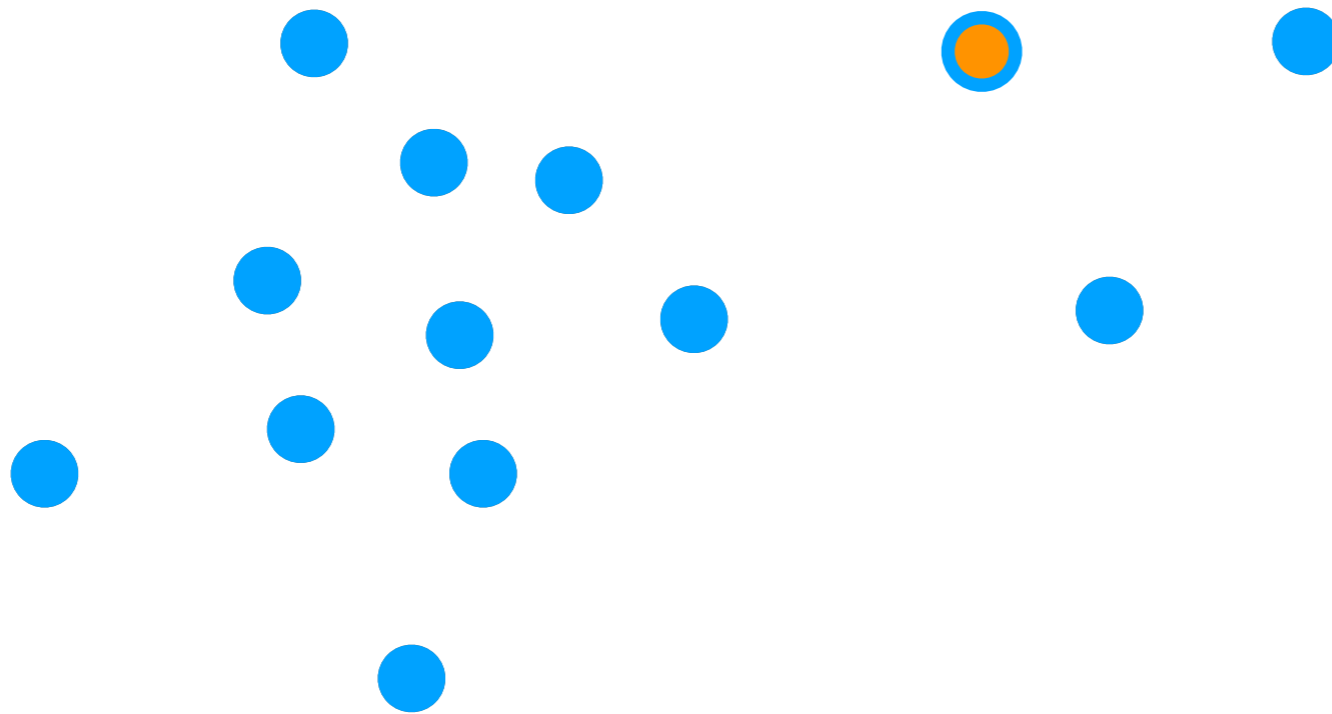
Example: choose k of the points uniformly at random to be initial guesses for cluster centers

(There are many ways to make the initial guesses)

k -means

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Example: choose k of the points uniformly at random to be initial guesses for cluster centers

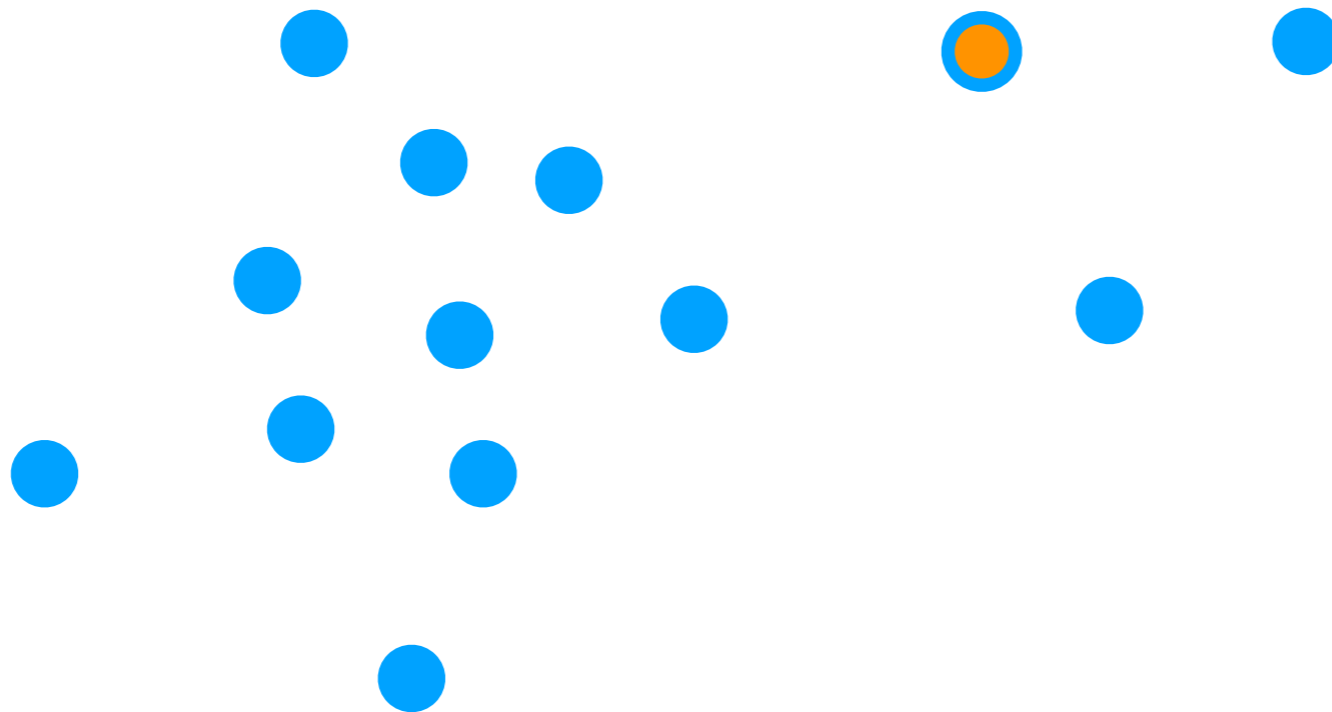
(There are many ways to make the initial guesses)

Step 2: Assign each point to belong to the closest cluster

k -means

Step 0: Pick k

We'll pick $k = 2$



Step 1: Pick guesses for where cluster centers are

Example: choose k of the points uniformly at random to be initial guesses for cluster centers

(There are many ways to make the initial guesses)

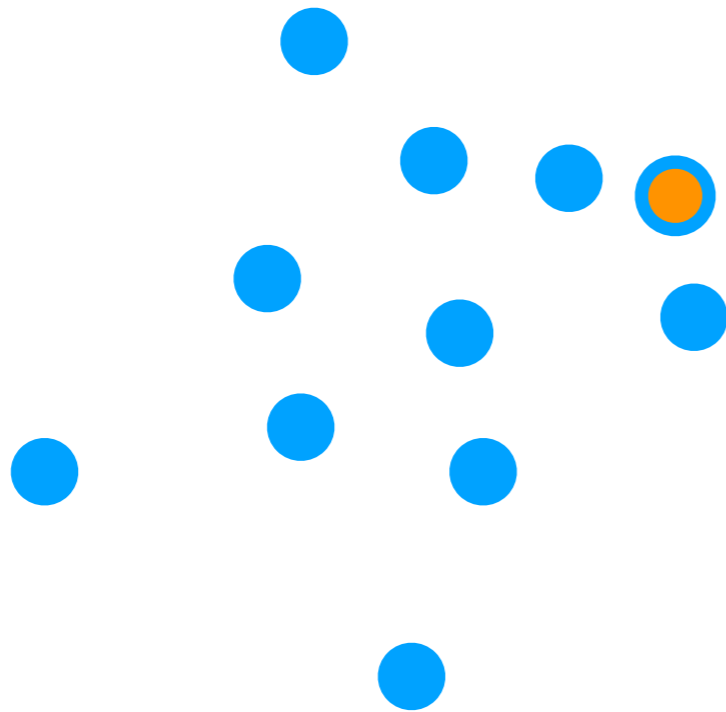
Step 2: Assign each point to belong to the closest cluster

Step 3: Update cluster means (to be the center of mass per cluster)

k -means

Step 0: Pick k

We'll pick $k = 2$



Step 1: Pick guesses for where cluster centers are



Example: choose k of the points uniformly at random to be initial guesses for cluster centers

(There are many ways to make the initial guesses)

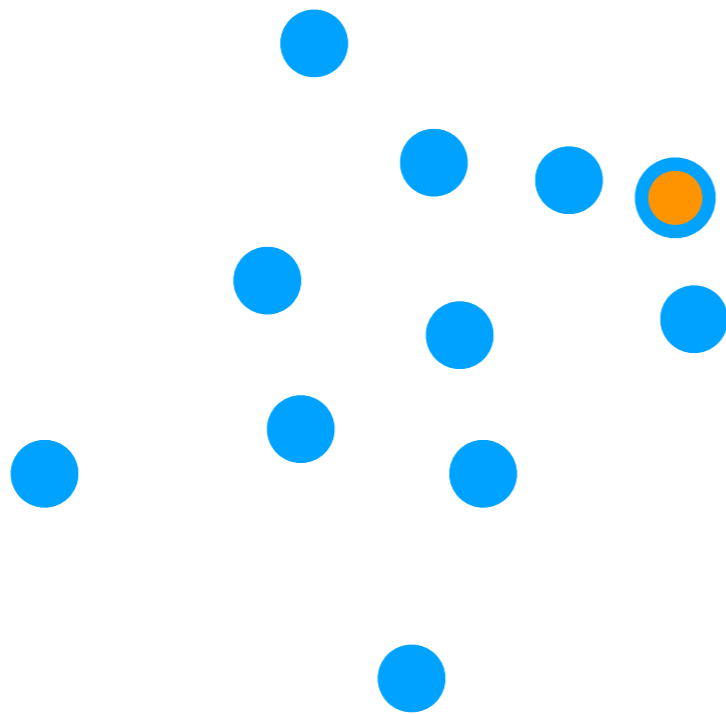
Step 2: Assign each point to belong to the closest cluster

Step 3: Update cluster means (to be the center of mass per cluster)

k -means

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Step 1: Pick guesses for where cluster centers are



Example: choose k of the points uniformly at random to be initial guesses for cluster centers

(There are many ways to make the initial guesses)

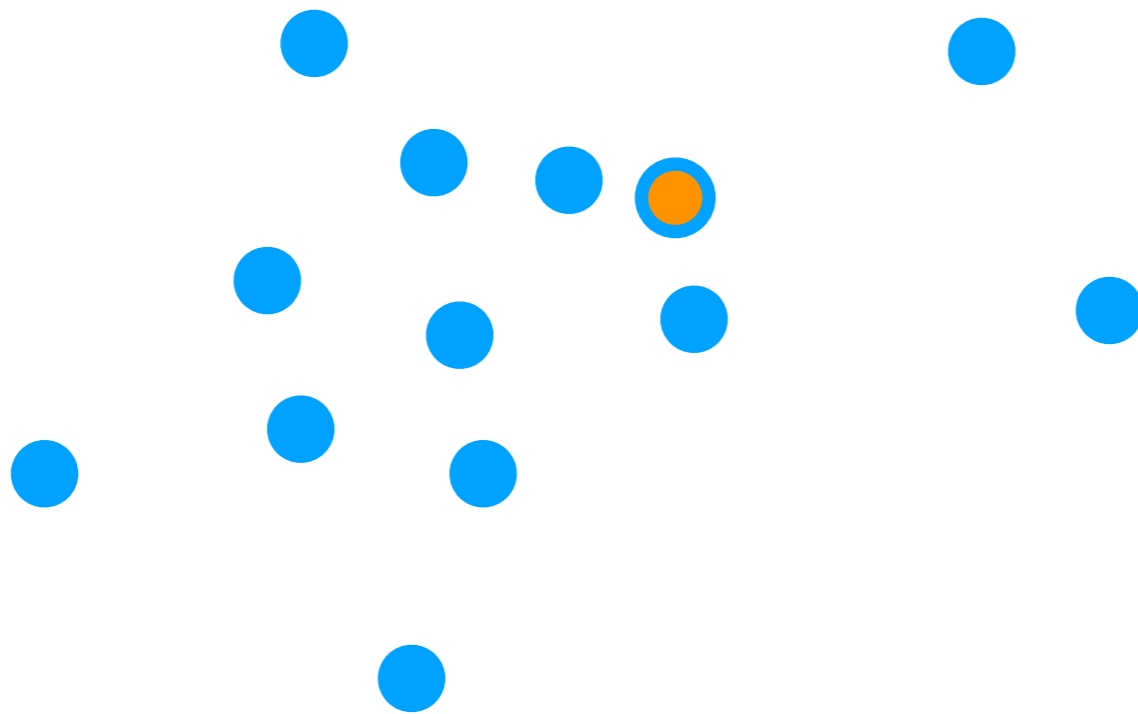
Repeat Step 2: Assign each point to belong to the closest cluster

Step 3: Update cluster means (to be the center of mass per cluster)

k -means

Step 0: Pick k

We'll pick $k = 2$



Step 1: Pick guesses for where cluster centers are

Example: choose k of the points uniformly at random to be initial guesses for cluster centers

(There are many ways to make the initial guesses)

Step 2: Assign each point to belong to the closest cluster

Repeat

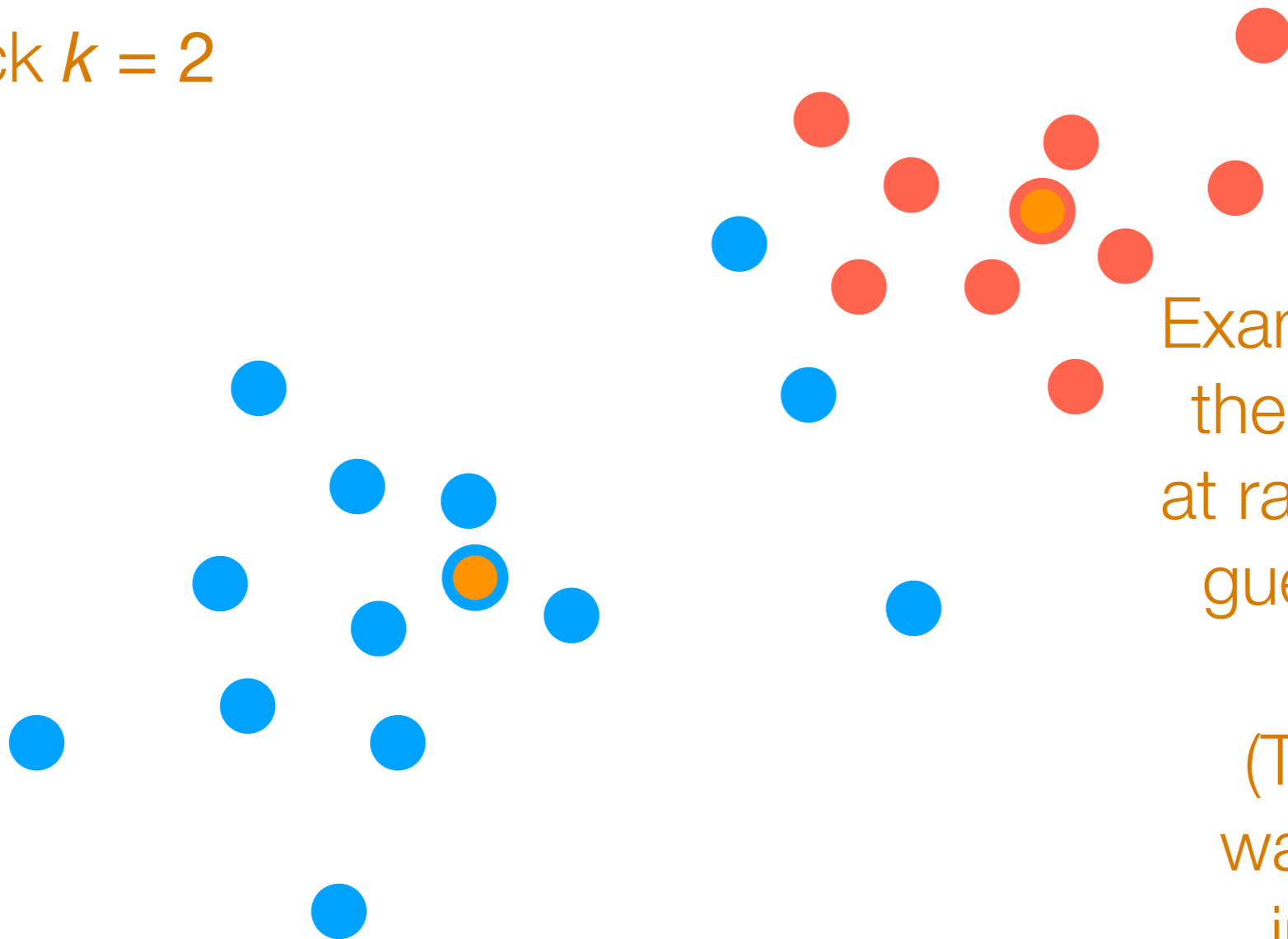
Step 3: Update cluster means (to be the center of mass per cluster)

k -means

Step 0: Pick k

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Step 1: Pick guesses for where cluster centers are



Example: choose k of the points uniformly at random to be initial guesses for cluster centers

(There are many ways to make the initial guesses)

Step 2: Assign each point to belong to the closest cluster

Repeat

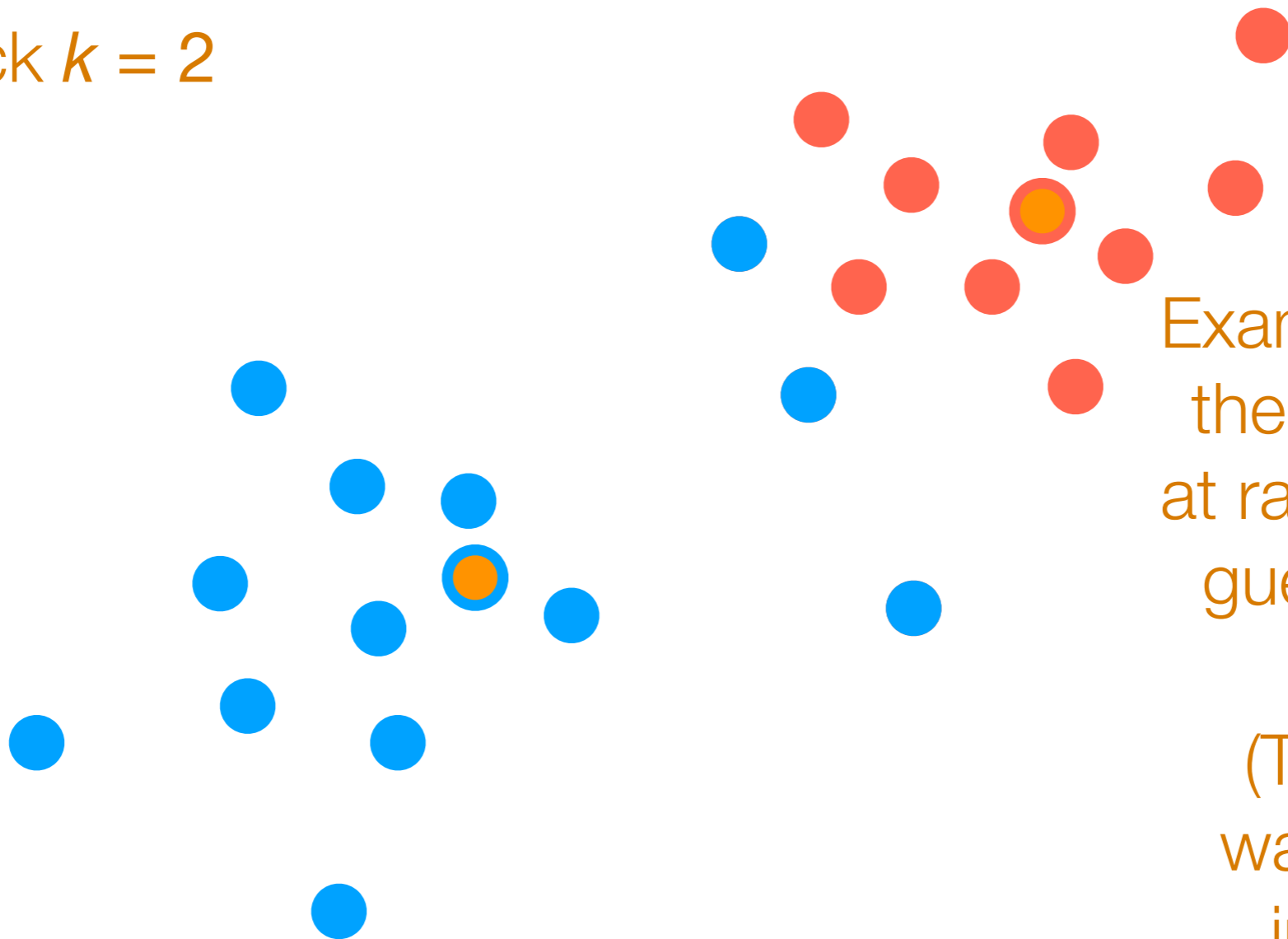
Step 3: Update cluster means (to be the center of mass per cluster)

k -means

Step 0: Pick k

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Example: choose k of the points uniformly at random to be initial guesses for cluster centers

(There are many ways to make the initial guesses)

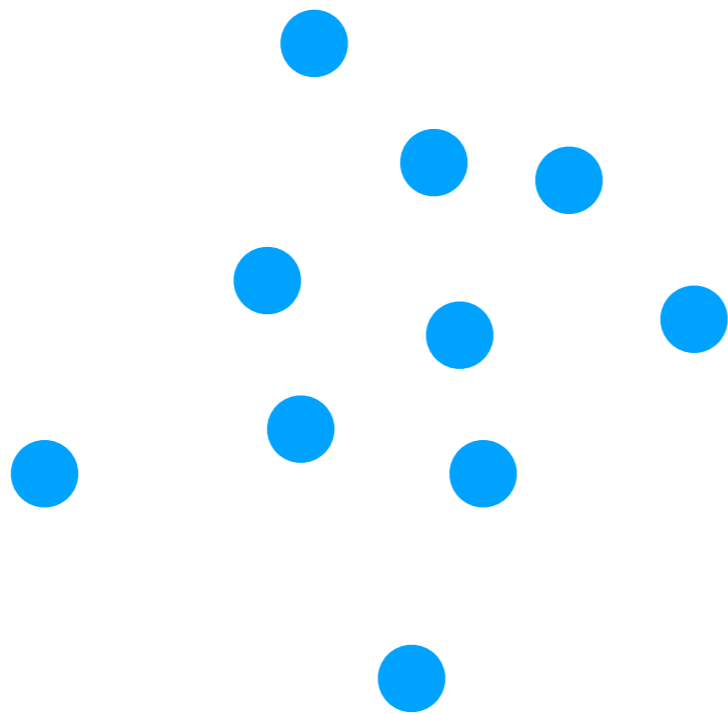
Repeat Step 2: Assign each point to belong to the closest cluster

Step 3: Update cluster means (to be the center of mass per cluster)

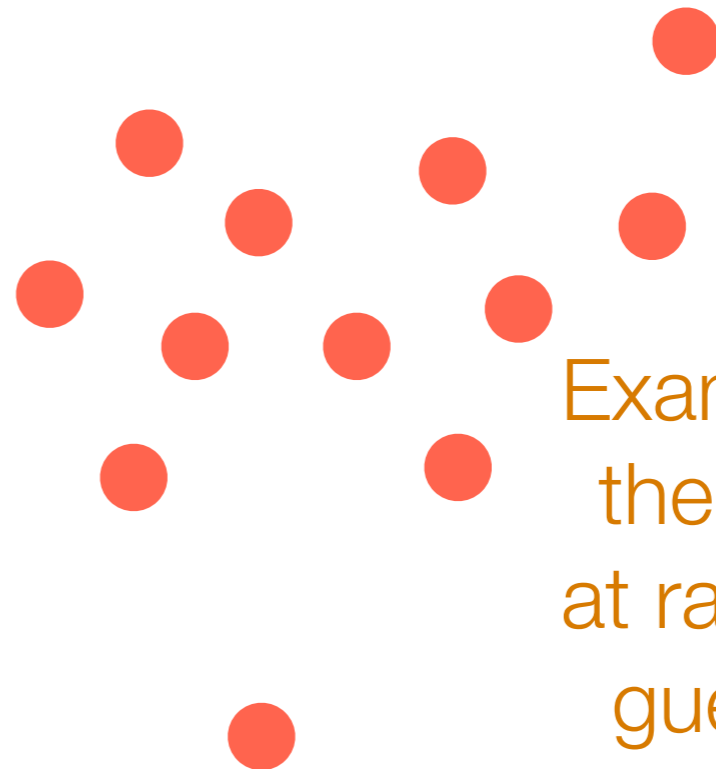
k -means

Step 0: Pick k

We'll pick $k = 2$



Step 1: Pick guesses for where cluster centers are



Example: choose k of the points uniformly at random to be initial guesses for cluster centers

(There are many ways to make the initial guesses)

Step 2: Assign each point to belong to the closest cluster

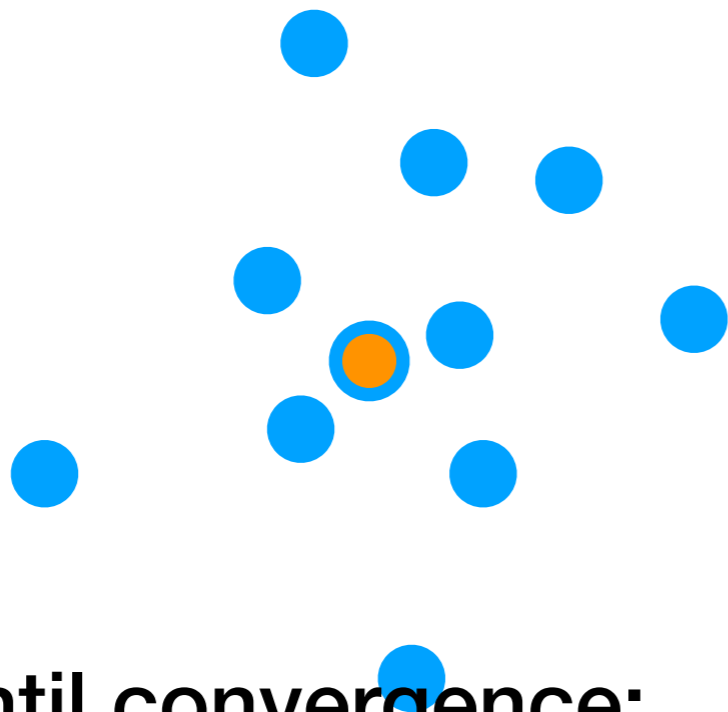
Repeat

Step 3: Update cluster means (to be the center of mass per cluster)

k -means

Step 0: Pick k

We'll pick $k = 2$



Step 1: Pick guesses for where cluster centers are



Example: choose k of the points uniformly at random to be initial guesses for cluster centers

(There are many ways to make the initial guesses)

Repeat until convergence:

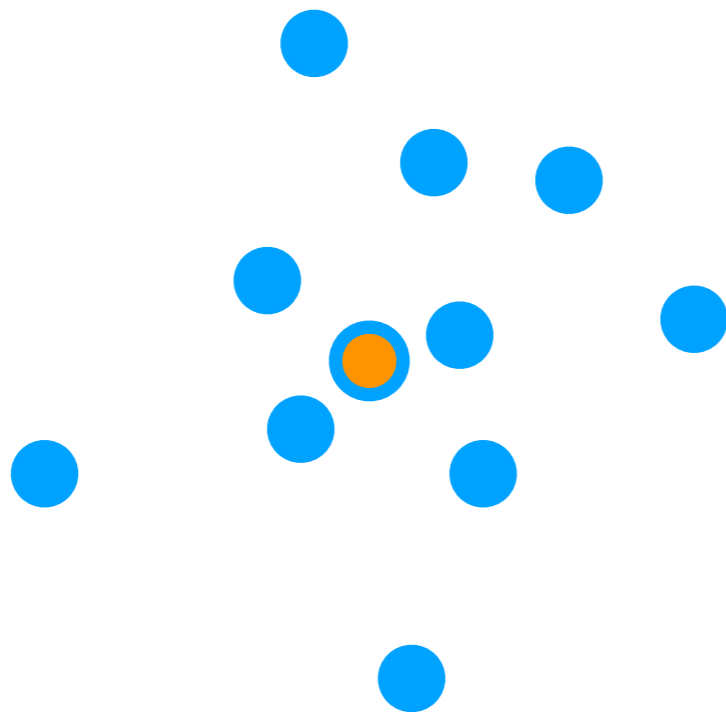
Step 2: Assign each point to belong to the closest cluster

Step 3: Update cluster means (to be the center of mass per cluster)

k-means

Final output: cluster centers, cluster assignment for every point

Remark: Very sensitive to choice of k and initial cluster centers



How to pick k ?

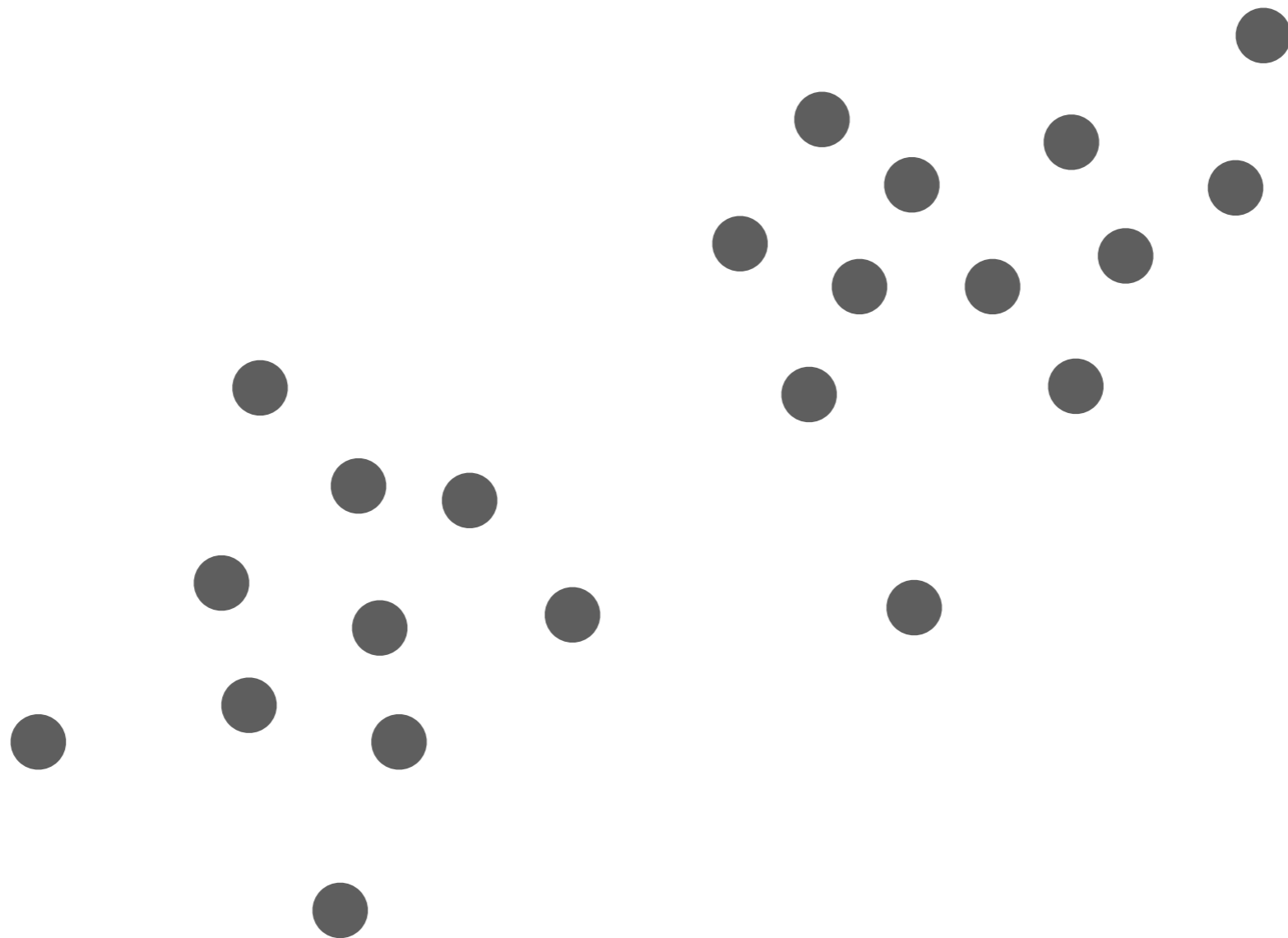
- Basic check: If you have really, really tiny clusters \Rightarrow decrease k
- More details later

Suggested way to pick initial cluster centers: “ k -means++” method (rough intuition: incrementally add centers; favor adding center far away from centers chosen so far)

When does *k*-means work well?

k-means is related to a more general model, which will help us understand *k*-means

Gaussian Mixture Model (GMM)



What random process could have generated these points?

Generative Process

Think of flipping a coin

each outcome: heads or tails

Each flip doesn't depend on any of the previous flips

Generative Process

Think of flipping a coin

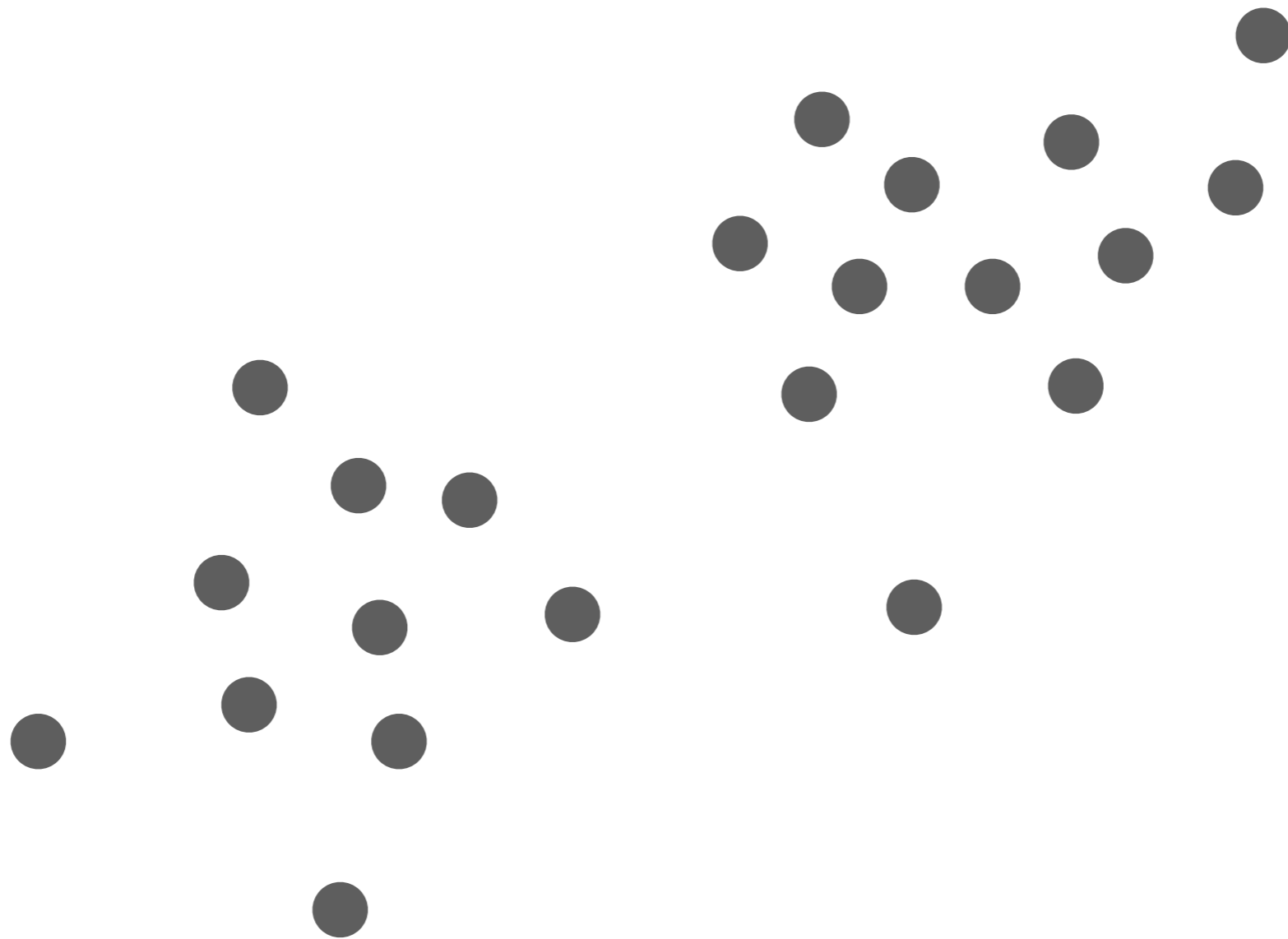
each outcome: 2D point

Each flip doesn't depend on any of the previous flips

Okay, maybe it's bizarre to think of it as a coin...

*If it helps, just think of it as you pushing a button and
a random 2D point appears...*

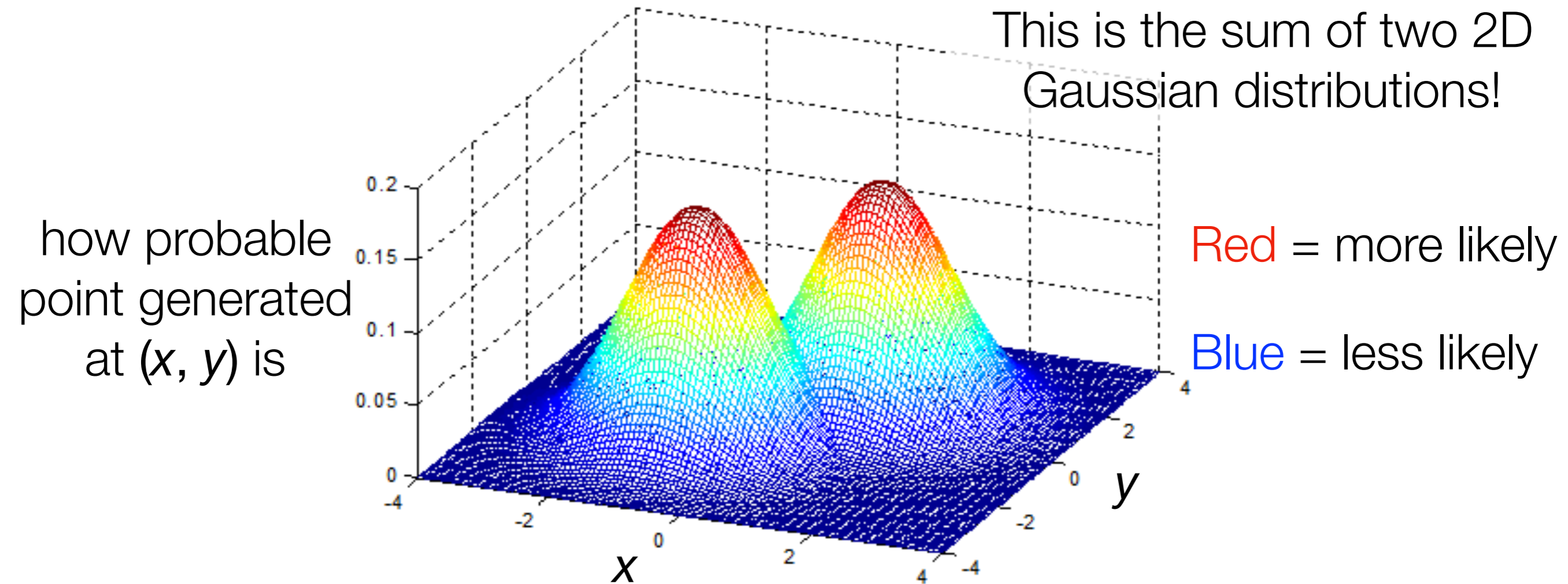
Gaussian Mixture Model (GMM)



We now discuss a way to generate points in this manner

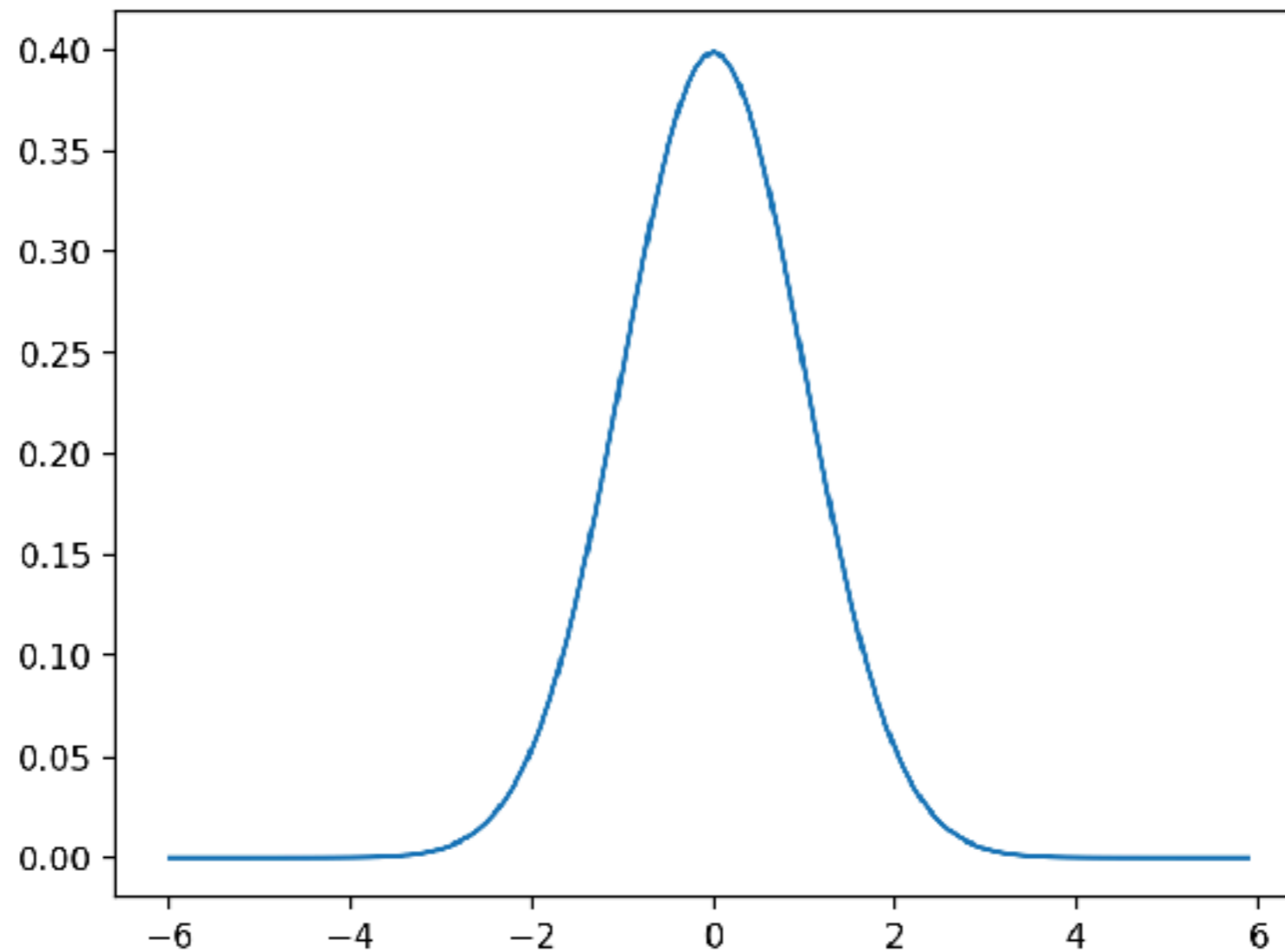
Gaussian Mixture Model (GMM)

Assume: points sampled independently from a probability distribution



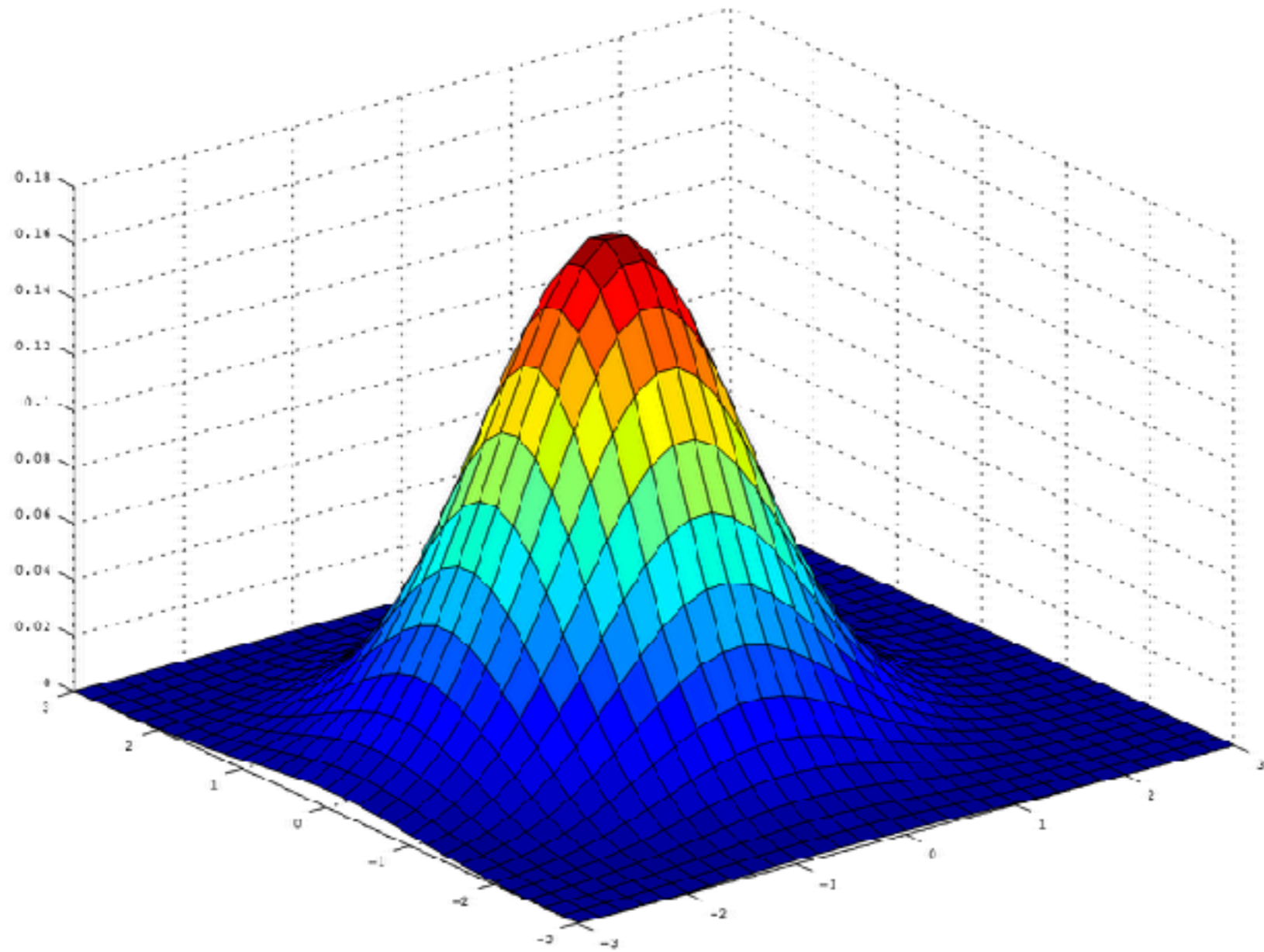
Example of a 2D probability distribution

Quick Reminder: 1D Gaussian



This is a 1D Gaussian distribution

2D Gaussian

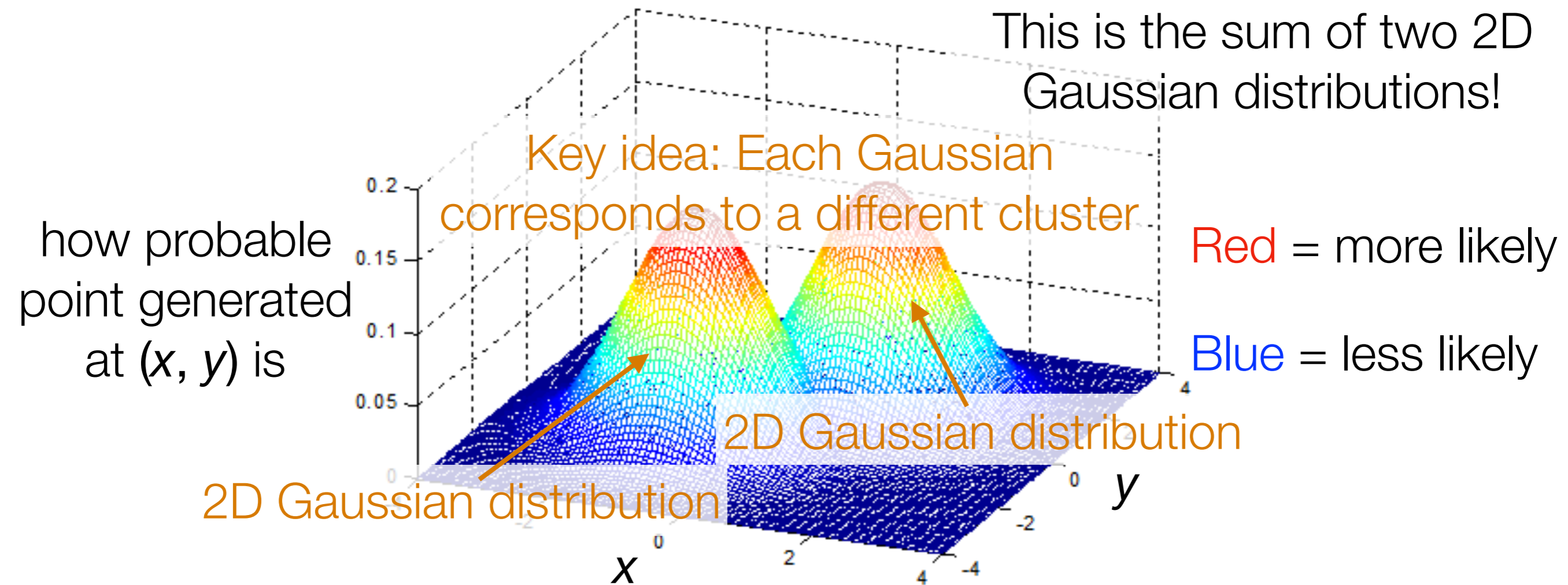


This is a 2D Gaussian distribution

Image source: <https://i.stack.imgur.com/OIWce.png>

Gaussian Mixture Model (GMM)

Assume: points sampled independently from a probability distribution



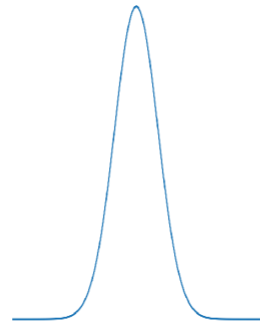
Example of a 2D probability distribution

Gaussian Mixture Model (GMM)

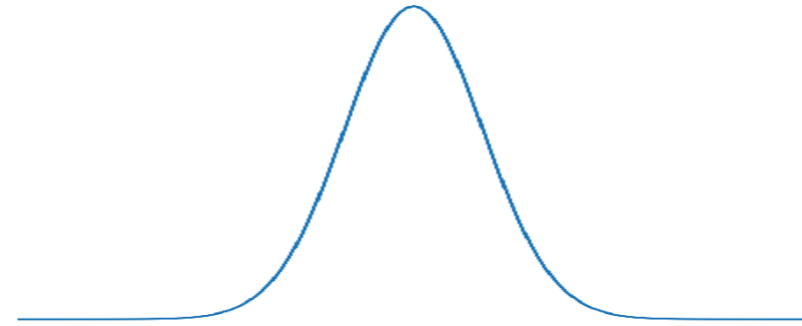
- For a fixed value k and dimension d , a GMM is the sum of k d -dimensional Gaussian distributions so that the overall probability distribution looks like k mountains (We've been looking at $d = 2$)
 - Each mountain corresponds to a different cluster
 - Different mountains can have different peak heights
 - One missing thing we haven't discussed yet: different mountains can have different shapes

2D Gaussian Shape

In 1D, you can have a skinny Gaussian or a wide Gaussian



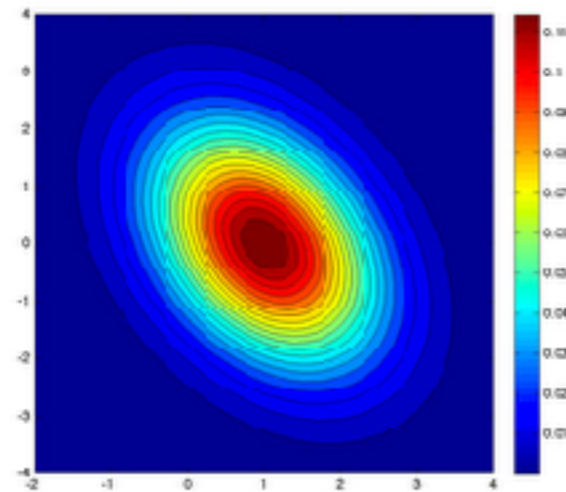
Less uncertainty



More uncertainty

In 2D, you can more generally have ellipse-shaped Gaussians

Ellipse enables
encoding relationship
between variables



Can't have arbitrary
shapes

Top-down view of an example 2D Gaussian distribution

Gaussian Mixture Model (GMM)

- For a fixed value k and dimension d , a GMM is the sum of k d -dimensional Gaussian distributions so that the overall probability distribution looks like k mountains (We've been looking at $d = 2$)
 - Each mountain corresponds to a different cluster
 - Different mountains can have different peak heights
 - Different mountains can have different ellipse shapes (captures "covariance" information)

Example: 1D GMM with 2 Clusters

Cluster 1

Probability of generating a point from cluster 1 = 0.5

Gaussian mean = -5

Gaussian std dev = 1

Cluster 2

Probability of generating a point from cluster 2 = 0.5

Gaussian mean = 5

Gaussian std dev = 1

What do you think this looks like?

Example: 1D GMM with 2 Clusters

Cluster 1

Probability of generating a point from cluster 1 = 0.5

Gaussian mean = -5

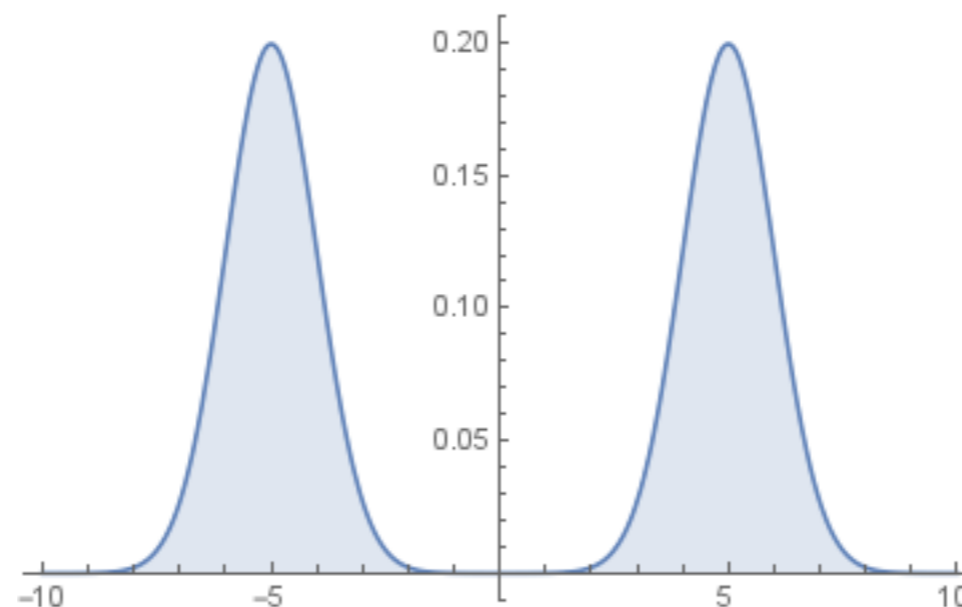
Gaussian std dev = 1

Cluster 2

Probability of generating a point from cluster 2 = 0.5

Gaussian mean = 5

Gaussian std dev = 1



Example: 1D GMM with 2 Clusters

Cluster 1

Probability of generating a point from cluster 1 = **0.7**

Gaussian mean = -5

Gaussian std dev = 1

Cluster 2

Probability of generating a point from cluster 2 = **0.3**

Gaussian mean = 5

Gaussian std dev = 1

What do you think this looks like?

Example: 1D GMM with 2 Clusters

Cluster 1

Probability of generating a point from cluster 1 = 0.7

Gaussian mean = -5

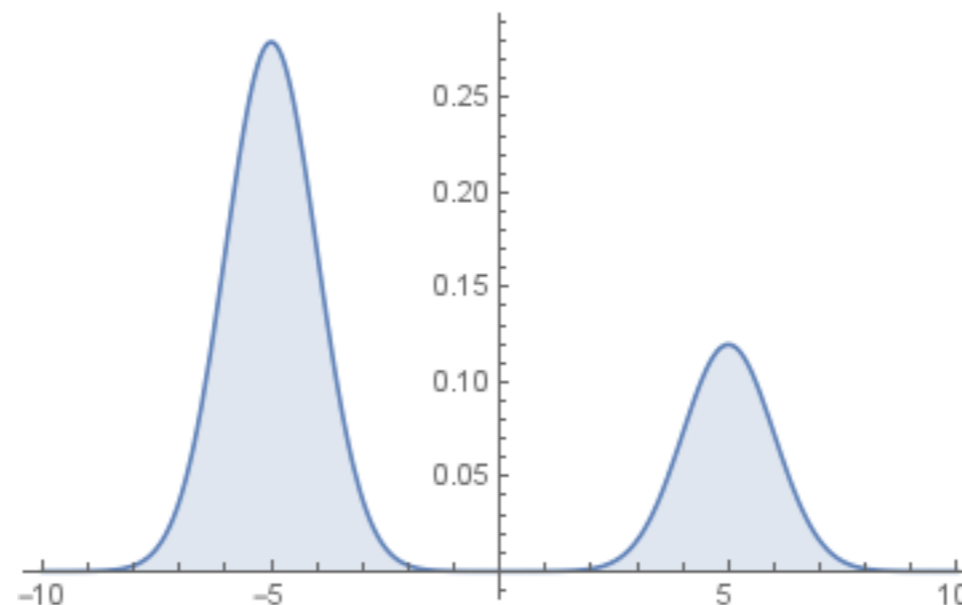
Gaussian std dev = 1

Cluster 2

Probability of generating a point from cluster 2 = 0.3

Gaussian mean = 5

Gaussian std dev = 1



Example: 1D GMM with 2 Clusters

Cluster 1

Probability of generating a point from cluster 1 = 0.7

Gaussian mean = -5

Gaussian std dev = 1

Cluster 2

Probability of generating a point from cluster 2 = 0.3

Gaussian mean = 5

Gaussian std dev = 1

How to generate 1D points from this GMM:

1. Flip biased coin (with probability of heads 0.7)
2. If heads: sample 1 point from Gaussian mean -5 , std dev 1
If tails: sample 1 point from Gaussian mean 5, std dev 1

Example: 1D GMM with 2 Clusters

Cluster 1

Probability of generating a point from cluster 1 = π_1

Gaussian mean = μ_1

Gaussian std dev = σ_1

Cluster 2

Probability of generating a point from cluster 2 = π_2

Gaussian mean = μ_2

Gaussian std dev = σ_2

How to generate 1D points from this GMM:

1. Flip biased coin (with probability of heads π_1)
2. If heads: sample 1 point from Gaussian mean μ_1 , std dev σ_1
If tails: sample 1 point from Gaussian mean μ_2 , std dev σ_2

Example: 1D GMM with k Clusters

Cluster 1

Probability of generating a point from cluster 1 = π_1

Gaussian mean = μ_1

Gaussian std dev = σ_1

...

Cluster k

Probability of generating a point from cluster k = π_k

Gaussian mean = μ_k

Gaussian std dev = σ_k

How to generate 1D points from this GMM:

1. Flip biased k -sided coin (the sides have probabilities π_1, \dots, π_k)
2. Let Z be the side that we got (it is some value $1, \dots, k$)
3. Sample 1 point from Gaussian mean μ_z , std dev σ_z

Example: 1D GMM with k Clusters

Cluster 1

Probability of generating a point from cluster 1 = π_1

Gaussian mean = μ_1

Gaussian std dev = σ_1

...

Cluster k

Probability of generating a point from cluster k = π_k

Gaussian mean = μ_k

Gaussian std dev = σ_k

How to generate 1D points from this GMM:

1. Flip biased k -sided coin (the sides have probabilities π_1, \dots, π_k)
2. Let Z be the side that we got (it is some value $1, \dots, k$)
3. Sample 1 point from Gaussian mean μ_z , std dev σ_z

Example: 2D GMM with k Clusters

Cluster 1

Cluster k

Probability of generating a point from cluster 1 = π_1

Probability of generating a point from cluster k = π_k

...

Gaussian mean = μ_1 2D point

Gaussian mean = μ_k 2D point

Gaussian **covariance** = Σ_1

Gaussian **covariance** = Σ_k

2x2 matrix

2x2 matrix

How to generate **2D** points from this GMM:

1. Flip biased k -sided coin (the sides have probabilities π_1, \dots, π_k)
2. Let Z be the side that we got (it is some value $1, \dots, k$)
3. Sample 1 point from Gaussian mean μ_Z , **covariance** Σ_Z

GMM with k Clusters

Cluster 1

Probability of generating a point from cluster 1 = π_1

Gaussian mean = μ_1

Gaussian covariance = Σ_1

...

Cluster k

Probability of generating a point from cluster k = π_k

Gaussian mean = μ_k

Gaussian covariance = Σ_k

How to generate points from this GMM:

1. Flip biased k -sided coin (the sides have probabilities π_1, \dots, π_k)
2. Let Z be the side that we got (it is some value $1, \dots, k$)
3. Sample 1 point from Gaussian mean μ_Z , covariance Σ_Z

High-Level Idea of GMM

- Generative model that gives a *hypothesized* way in which data points are generated

In reality, data are unlikely generated the same way!

In reality, data points might not even be independent!



“All models are wrong, but some are useful.”

–George Edward Pelham Box

Photo: “George Edward Pelham Box, Professor Emeritus of Statistics, University of Wisconsin-Madison” by DavidMCEddy is licensed under CC BY-SA 3.0

High-Level Idea of GMM

- Generative model that gives a *hypothesized* way in which data points are generated

In reality, data are unlikely generated the same way!

In reality, data points might not even be independent!

- Learning ("fitting") the parameters of a GMM
 - Input: d -dimensional data points, your guess for k
 - Output: $\pi_1, \dots, \pi_k, \mu_1, \dots, \mu_k, \Sigma_1, \dots, \Sigma_k$
- *After* learning a GMM:
 - For *any* d -dimensional data point, can figure out probability of it belonging to each of the clusters

How do you turn this into a cluster assignment?